

ION GNSS+ 2016

# MOVING FORWARD TO THE FUTURE LOW-COST PPP PARADIGM

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Session D5b: Next-generation Sensors in Phones, Tablets and Wearables

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# OUTLINE

GNSS Receivers & PPP Trends

magicGNSS Evolution towards Low-Cost precise positioning

Preliminary experimentation results

Conclusions and Way-Forward

# ION GNSS+ 2016 PPP & GNSS RECEIVERS TRENDS

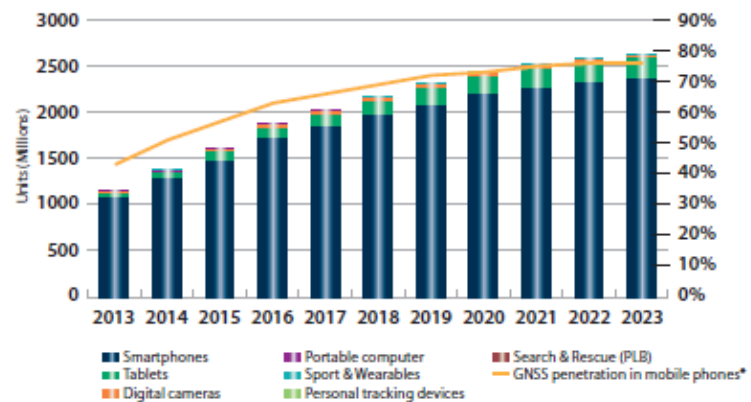
# GNSS RECEIVERS MARKET

- Two markets: high-end receivers and low-cost receivers
  - Current expected performances: centimeter level vs meter level
  - Price: \$10000s vs \$1-100
  
- Huge growth of the number of sold low cost receivers during the last years thanks to mobile devices
  - Single frequency
  - Integrated Antenna
  
- Improve positioning service performances for low-cost users.
  - Phase measurements provision in smartphones' chipsets
  - Multifrequency
  - Implement advance positioning algorithm
  - Reduce power consumption



**Price:**  
**\$10K-\$20K**

**Price:**  
**\$1-\$100**

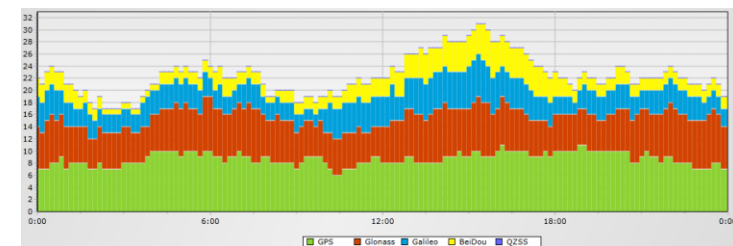
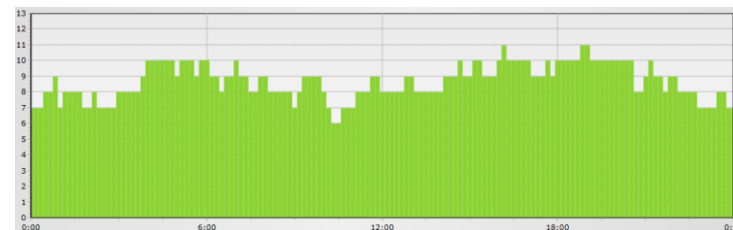
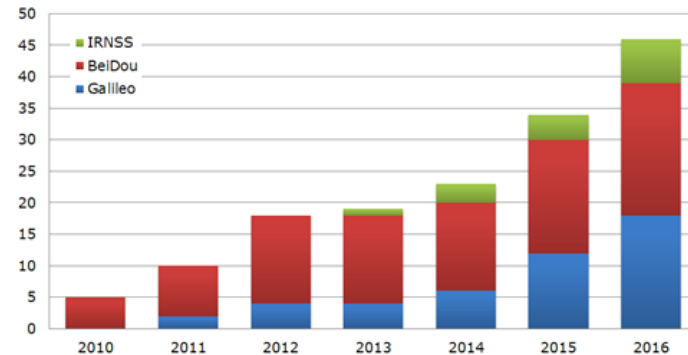


<https://www.gsa.europa.eu/market/market-report>



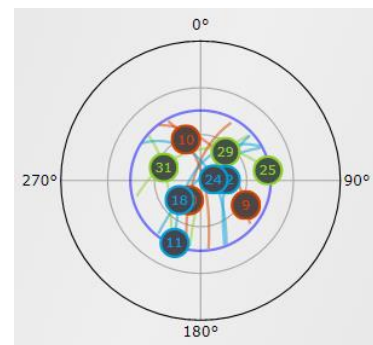
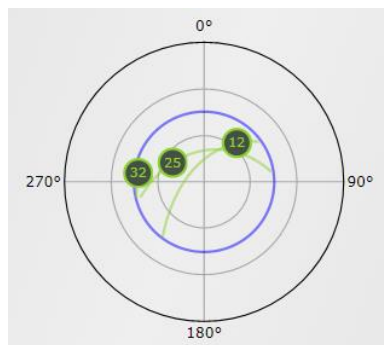
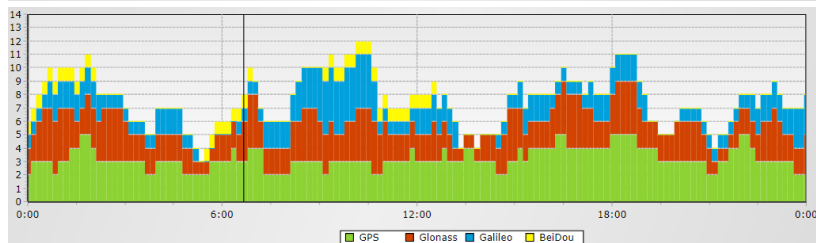
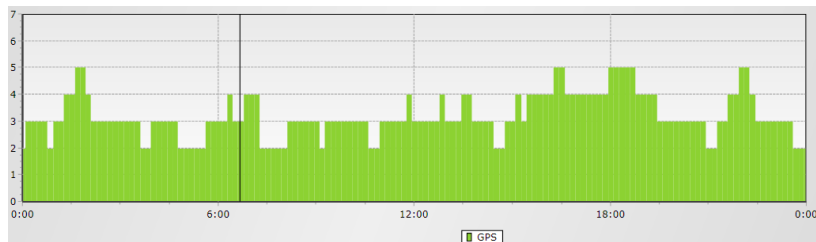
# PPP TECHNIQUES EVOLUTION

- MultiGNSS and GNSS modernization:
  - Better achievable positioning and timing solution
  - Drastically **increases the satellite availability**
  - Better performances in challenging environments
  
- Single-Frequency Processing:
  - Explore new markets
  - Cost-saving alternative
  
- Gap-bridging:
  - Avoid reconvergences
  - Achieve solution continuity
  
- Reduce Convergence Time
  - Major PPP drawback.
  - One of the main topic being investigated by the industry



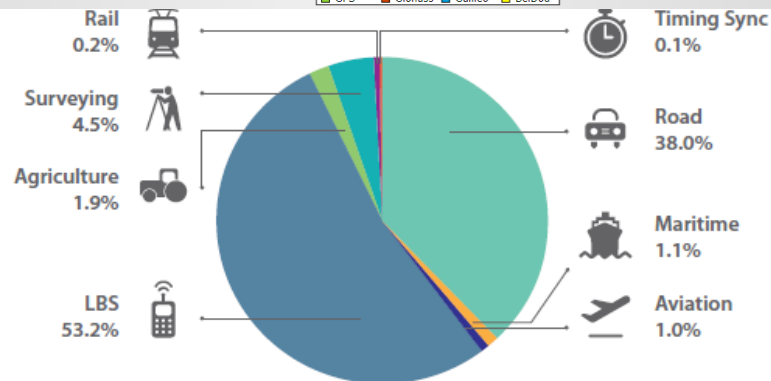
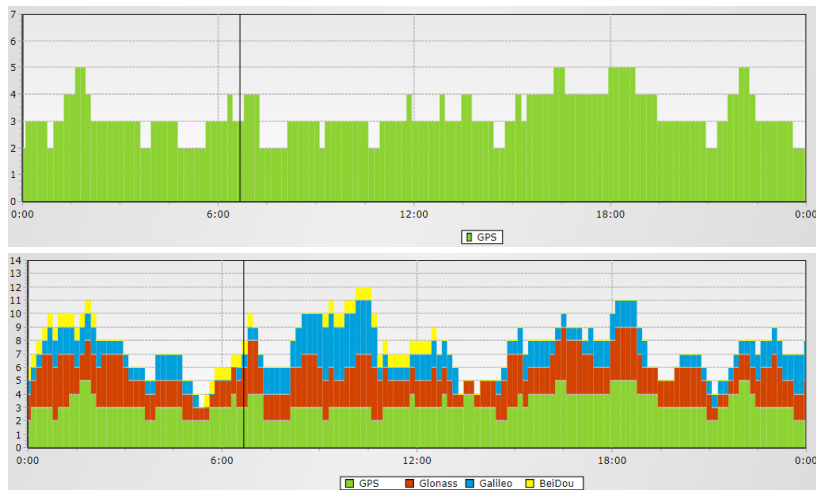
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- Single-Frequency Processing:
  - Explore **new markets**
  - Cost-saving alternative
  
- Gap-bridging:
  - Avoid reconvergences
  - Achieve solution continuity, not only from signal losses, but from data losses
  
- Reduce Convergence Time
  - Major PPP drawback.
  - One of the main topic being investigated by the industry



<https://www.gsa.europa.eu/market/market-report>

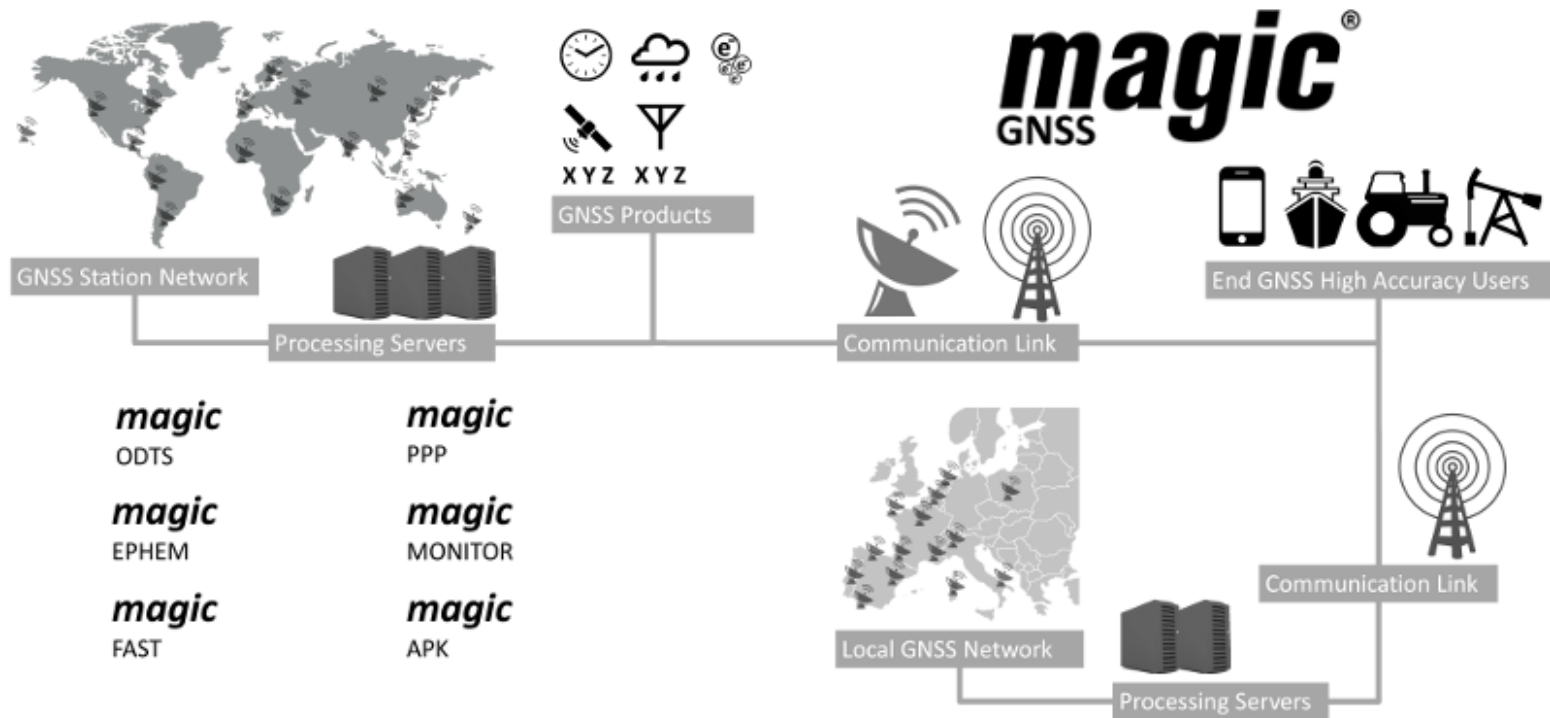


**ION GNSS+ 2016**  
**magicGNSS**  
**EVOLUTION**  
**TOWARDS**  
**LOW-COST**  
**PRECISE**  
**POSITIONING**



# magicGNSS' REAL TIME INFRASTRUCTURE

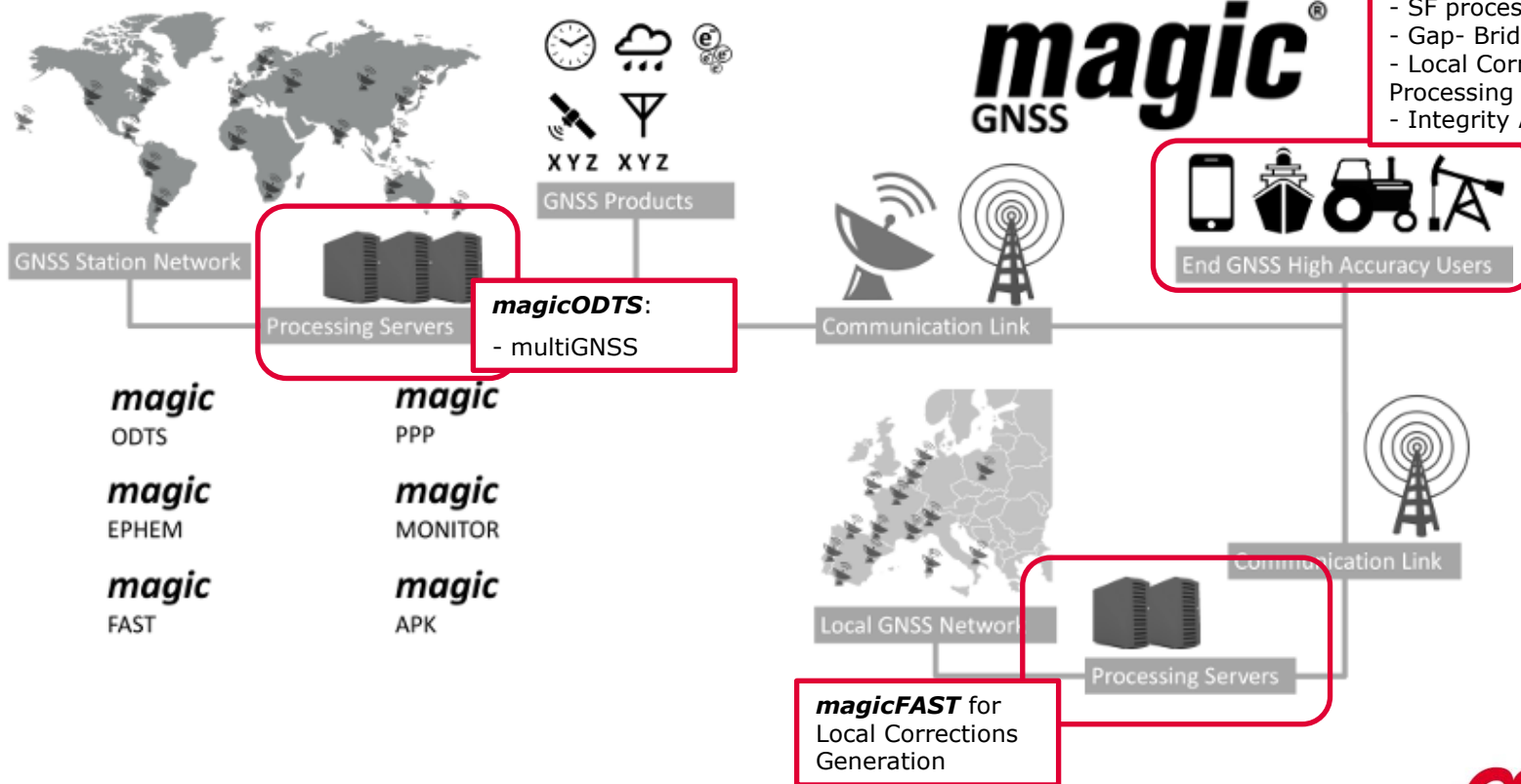
## END-TO-END PPP SERVICE



# magicGNSS' REAL TIME INFRASTRUCTURE

## UPGRADES FOR LOW-COST PPP

- magicPPP** capabilities:
- MultiGNSS
  - SF processing
  - Gap- Bridging
  - Local Corrections Processing
  - Integrity Algorithm



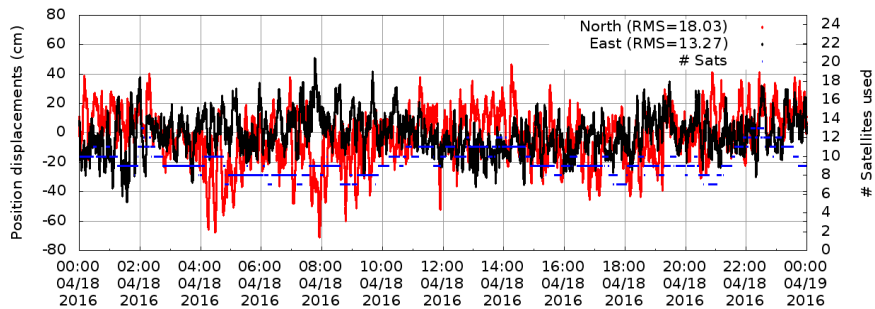
# magicPPP EVOLUTION

## ■ MultiGNSS and SF processing

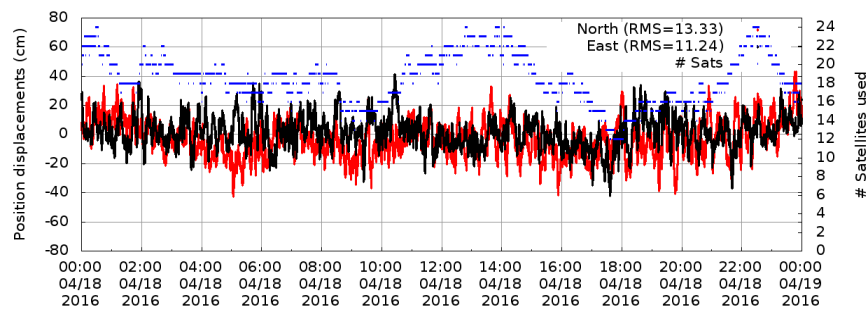
- Both server and client sides support multiGNSS processing (GPS, GLONASS, Galileo, BeiDou and QZSS)
- Client upgraded for working on single-frequency mode

uBlox m8t + Geodetic antenna

SF-PPP G-only



SF-PPP GRE

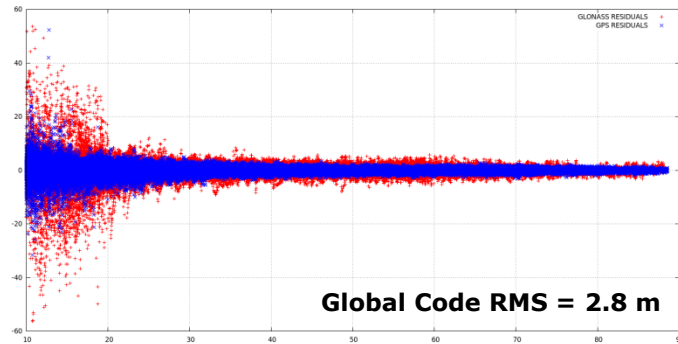


**Horizontal Accuracy below 15cm RMS !!**

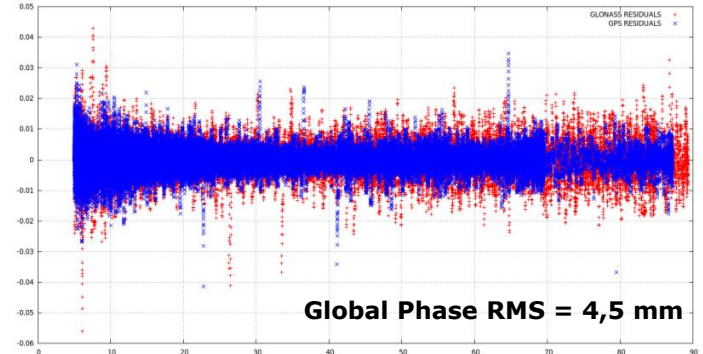
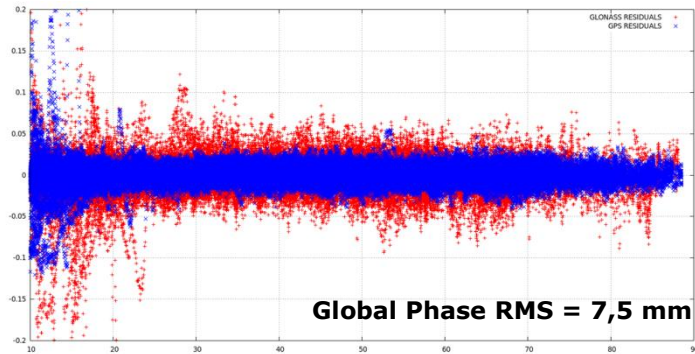
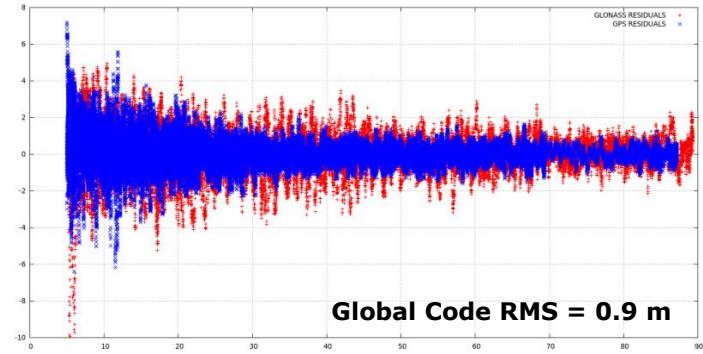
# magicPPP EVOLUTION

- Strong R+D effort for improving the PPP accuracy with cheap antennae (patch and device integrated) and low cost receivers

**uBlox m8n + Patch antenna**



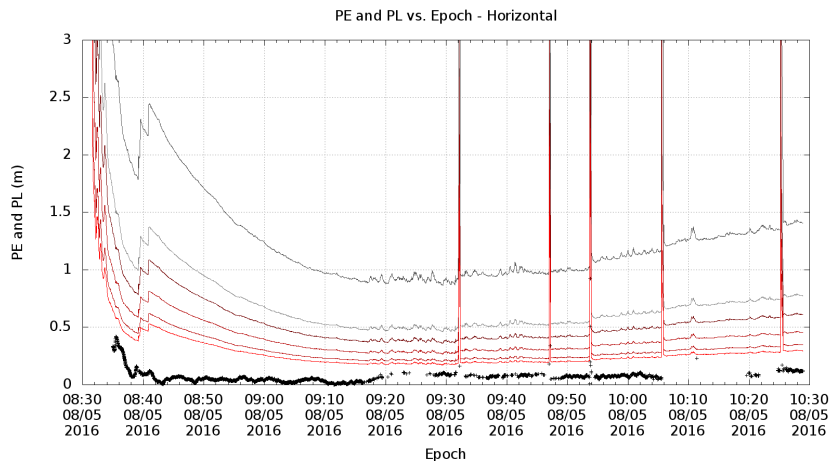
**uBlox m8n + Geodetic antenna**



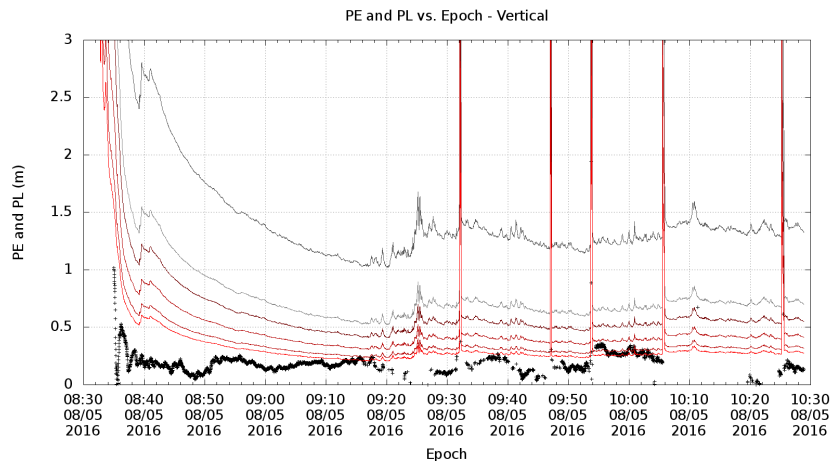
# magicPPP EVOLUTION

## ■ Integrity algorithm

- Algorithm developed for positioning based on Kalman filters, whereas the historical approach is focused on batch processing.
- Provides horizontal and vertical Protection Levels for bounding the error
- Proven to provide very good results under challenging conditions



PE (TIR=1e-07) — PL(TIR=0.0001) — PL(TIR=0.01) — PL(TIR=0.1) —  
 PL(TIR=0.001) — PL(TIR=0.05)

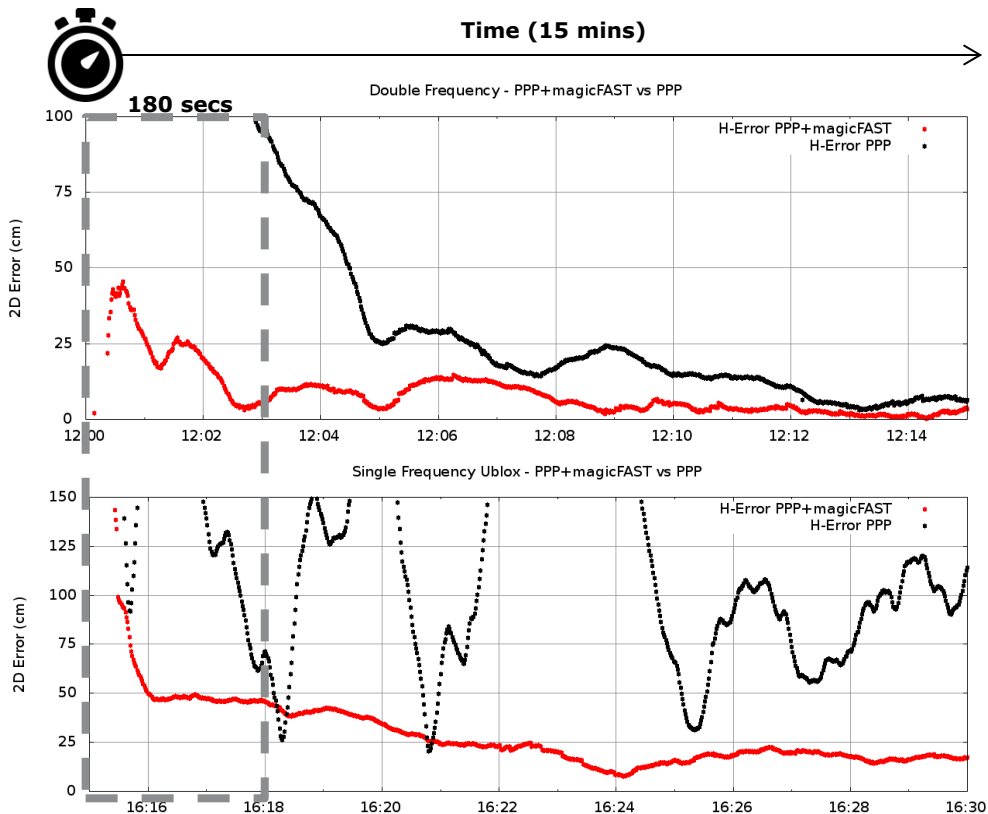


PE (TIR=1e-07) — PL(TIR=0.0001) — PL(TIR=0.01) — PL(TIR=0.1) —  
 PL(TIR=0.001) — PL(TIR=0.05)



# magicFAST – REGIONAL CORRECTIONS

- **magicFAST** is a solution for convergence time improvement
  - Wide regions service with a reduce number of monitor stations
  - Significant reduction in convergence time
  - Improvement in solution performances
  
- PPP accuracy after 180 seconds is:
  - Below 20 cm horizontal accuracy in DF-PPP
  - Below 50 cm horizontal accuracy in SF-PPP



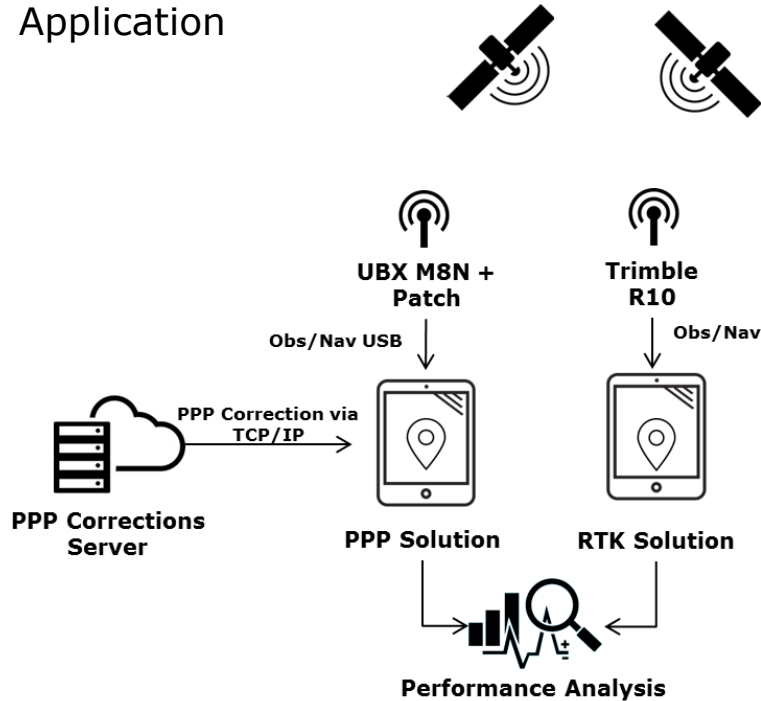
# ION GNSS+ 2016 EXPERIMENTATION





# DEVICES UNDER TESTING

- Reference trajectory: Trimble R10 + RTKLib
- Device Tested: uBlox NEO-M8N (GPS+GLONASS) with antenna patch + PPP Android Application



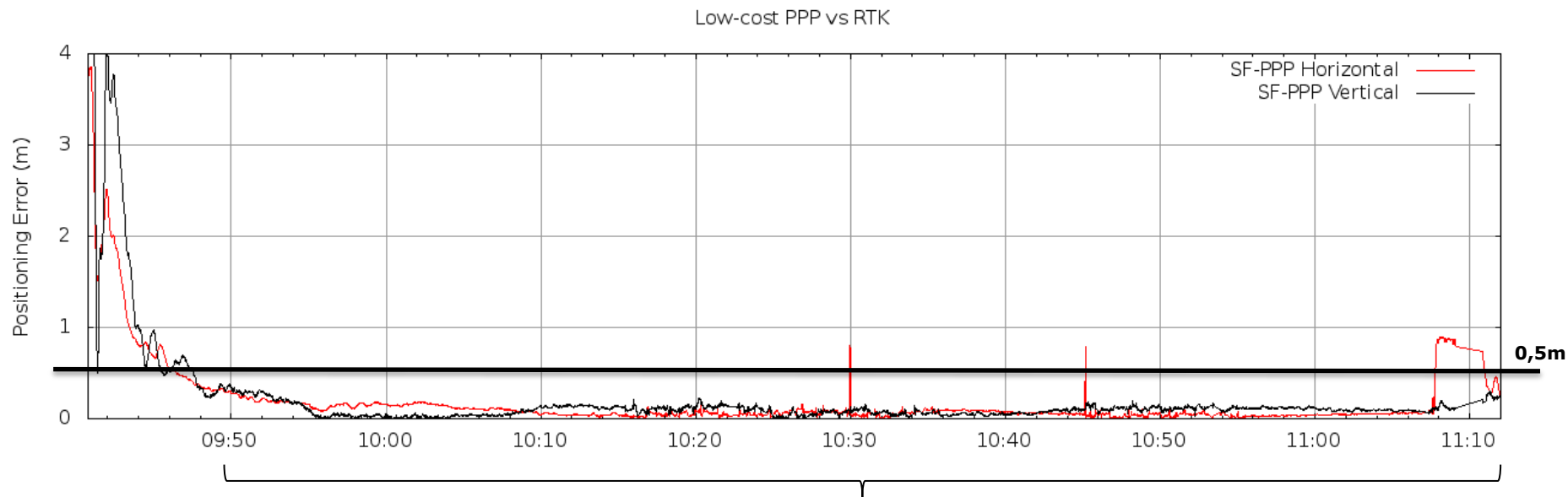
# TEST #1 – DESCRIPTION

- Kinematic scenario:
  - Open sky + urban conditions
  - Including high-way
  - Duration ~1,5 hours
- NEO-M8N+patch and Trimble R10 placed on top of a car
- Reference trajectory obtained with Trimble R10 + RTKLib. Applied correction between antenna positions.
- Local corrections:
  - *magicFAST*



# TEST #1 – RESULTS

- Horizontal convergence below 0.5m in less than 3 minutes
- Vertical convergence below 0.5m in less than 10 minutes



**RMS Horizontal: 0.107**  
**RMS Vertical: 0.110**



# TEST #2 – DESCRIPTION

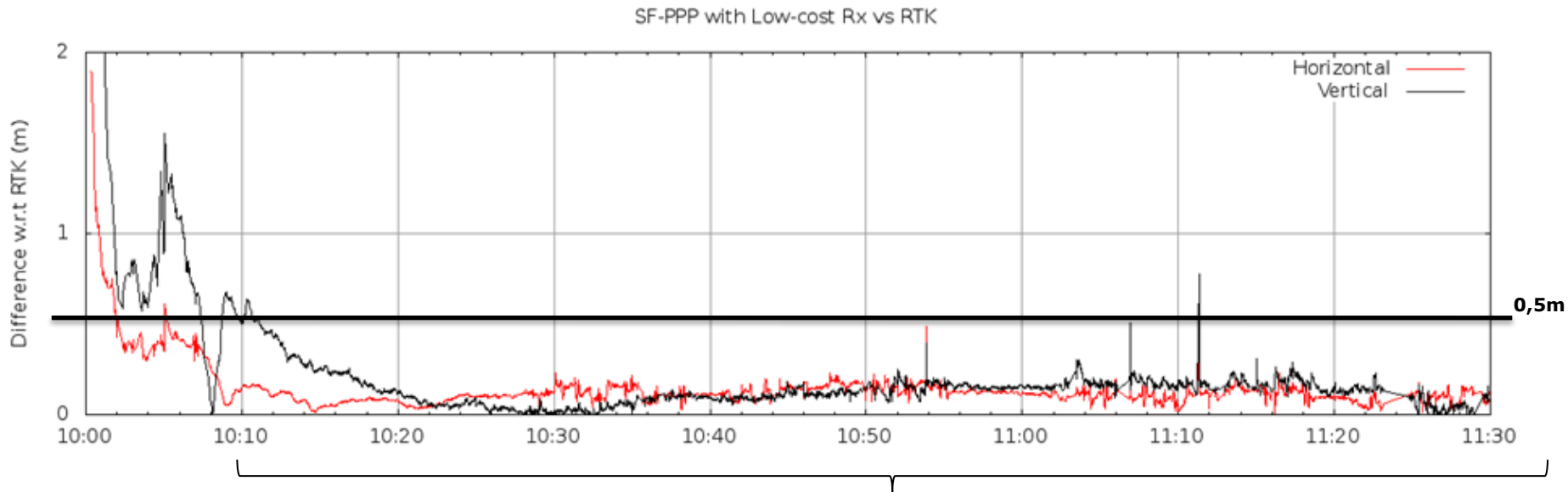
- Kinematic scenario:
  - Open sky + urban conditions
  - Duration ~1,5 hours
- NEO-M8N and Trimble R10 placed on top of a car
- Reference trajectory obtained with Trimble R10 + RTKLib. Applied correction between antenna positions.
- Local corrections:
  - *magicFAST*





# TEST #2 – RESULTS

- Horizontal convergence below 0.5m in less than 3 minutes
- Vertical convergence below 0.5m in ~10 minutes



**RMS Horizontal: 0.089**  
**RMS Vertical: 0.169**



# TEST #2 - RESULTS





# TEST #2 - RESULTS



# ION GNSS+ 2016 CONCLUSIONS



# CONCLUSIONS AND WAY-FORWARD

- Low-cost PPP is possible
  - Antenna+receiver equipment cost < \$100
  - Achievable accuracy below 0.40 m horizontal.
- Fast convergence both for SF and DF PPP thanks to ***magicFAST***
  - Local Corrections
- Integrity algorithm implemented and integrated within the PPP algorithm
- Future evolutions of the system
  - Processing of the GNSS data gathered by the chipset of the mobile and tablets → Android 7 Nougat will ease this step!!



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# THANK YOU



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