

ION GNSS 2015

Advanced GNSS Algorithms and Services Based on Highly-stable On-board Clocks

SEPTEMBER 16TH , 2015 - ION GNSS 2015, TAMPA, FLORIDA, USA

SESSION E2b: Advanced Technologies in High Precision GNSS Positioning 2

C. García
M. D. Laínez
P. Navarro
I. Rodríguez
G. Tobías

© GMV, 2015 Property of GMV
All rights reserved



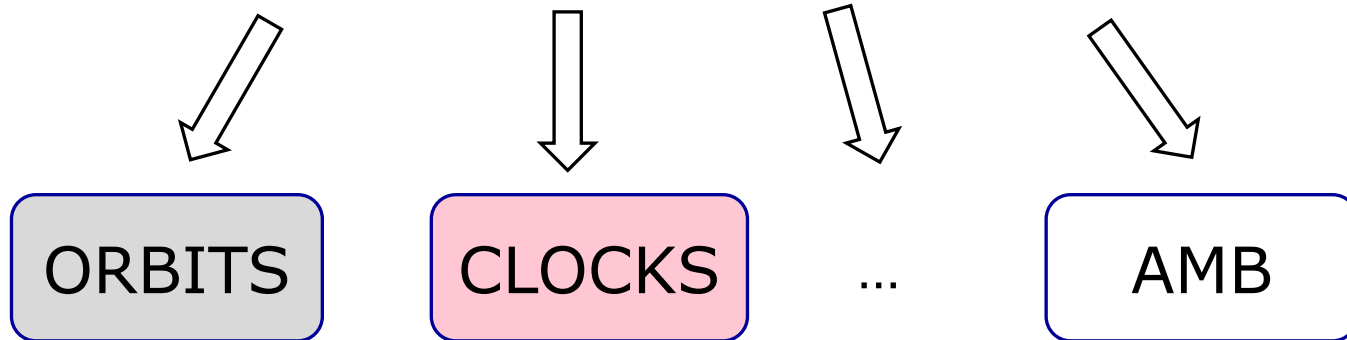
OUTLINE

- Introduction and objective
- Satellite clocks modelling
- Preliminary Results
- Conclusions

INTRODUCTION AND OBJECTIVE

ORBIT AND CLOCK ESTIMATION

Measurements = Information



State vector +
highly constrained
SRP parameters

Independent
parameter at each
epoch ('snapshot')

CONVENTIONAL OD&TS PROCESS

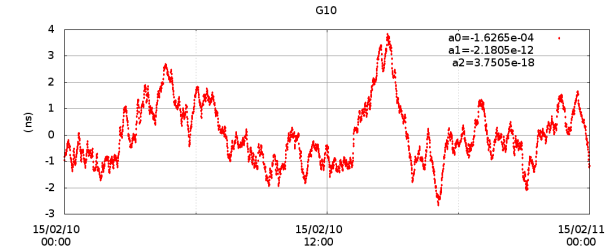
Snapshot estimation → huge amount of information

Relatively large tracking station networks are needed

IGS Analysis Centre	Reference Network size
CODE	240
NRCan	80
ESOC	150
GFZ	200
JPL	80
MIT	300
NGS	200
SIO	290
Service Provider	Reference Network size
FUGRO	>100
TRIMBLE	100
VERIPOS	74

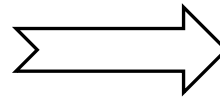
SATELLITE CLOCKS

Atomic clocks on board satellites are highly stable



Behavior

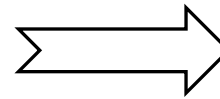
Random,
no pattern



Estimation

Snapshot

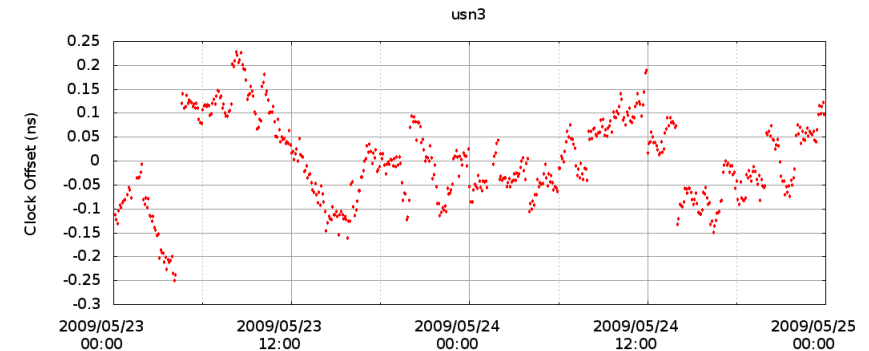
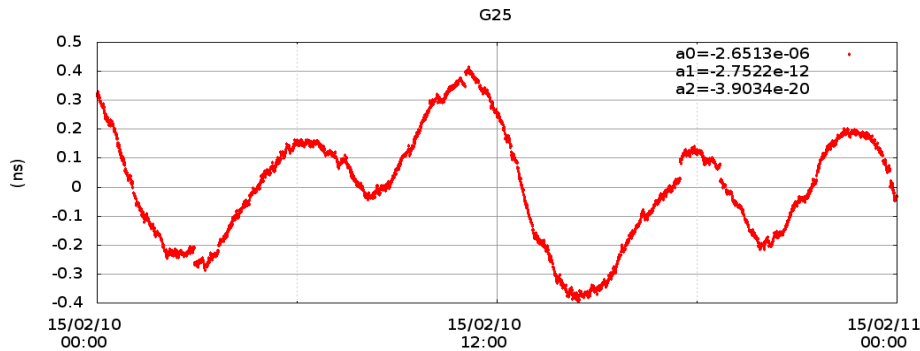
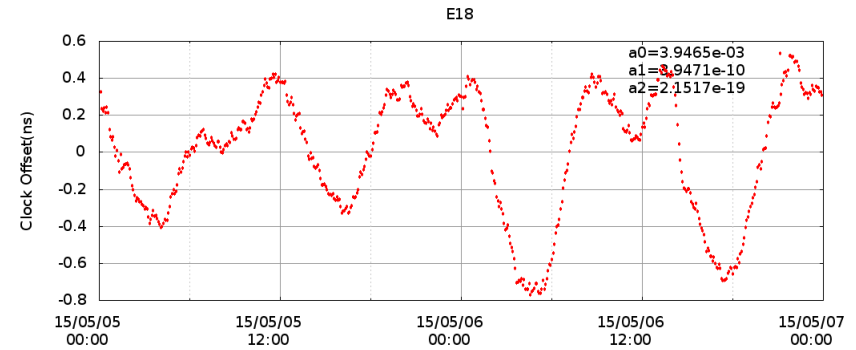
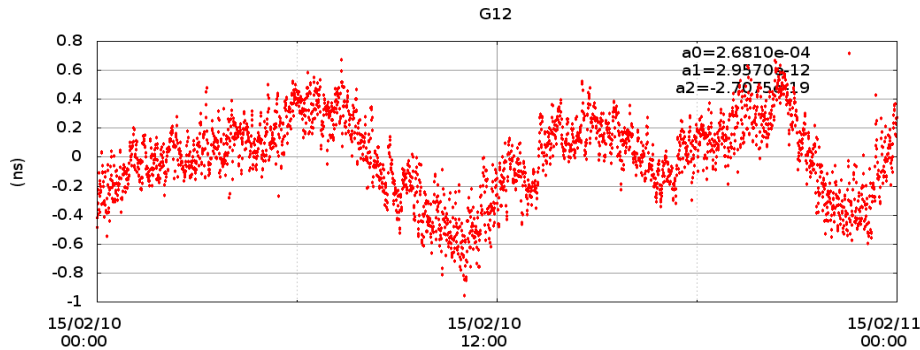
High stability,
clear pattern



?

SATELLITE CLOCKS

Satellite clock stability keeps improving

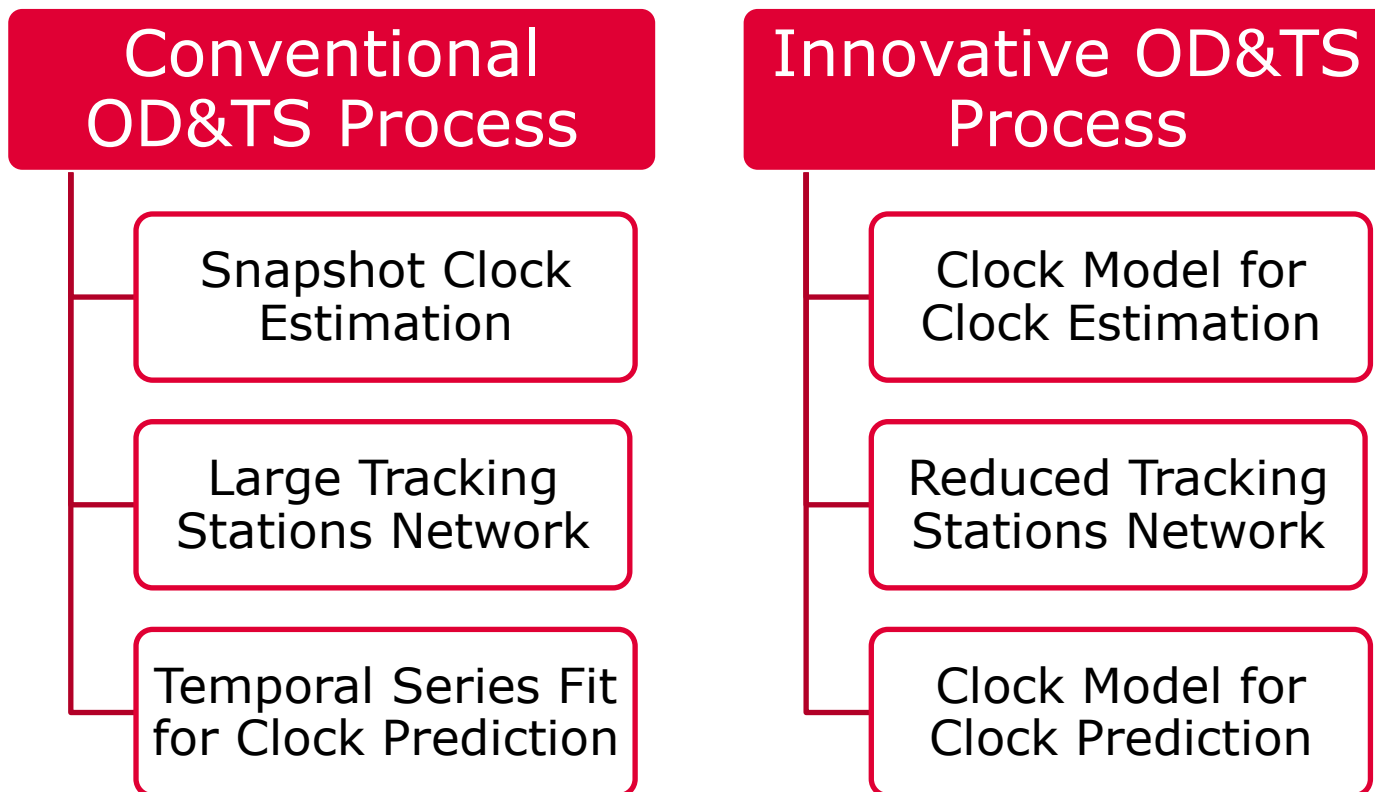
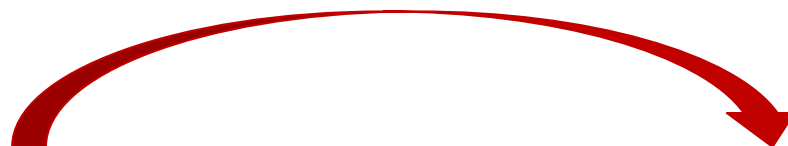


Rb

PHM

OBJECTIVE

Maintain performances



SATELLITE CLOCKS MODELLING

SATELLITE CLOCKS

CLOCKS BEHAVIOR

```
graph TD; A[CLOCKS BEHAVIOR] --- B[AFS]; A --- C[GNSS effects]; A --- D[Systematic]; A --- E[Stochastic]
```

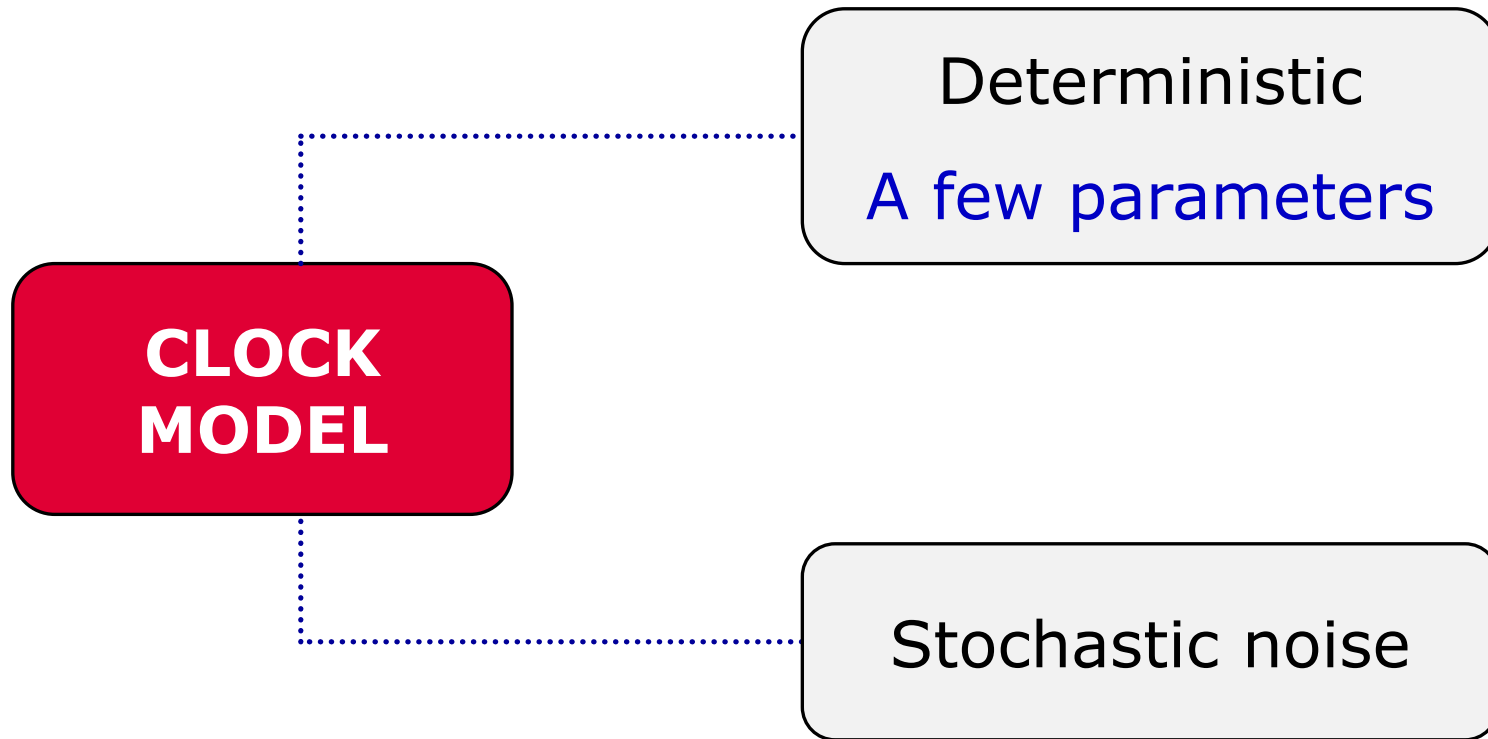
AFS

GNSS
effects

Systematic

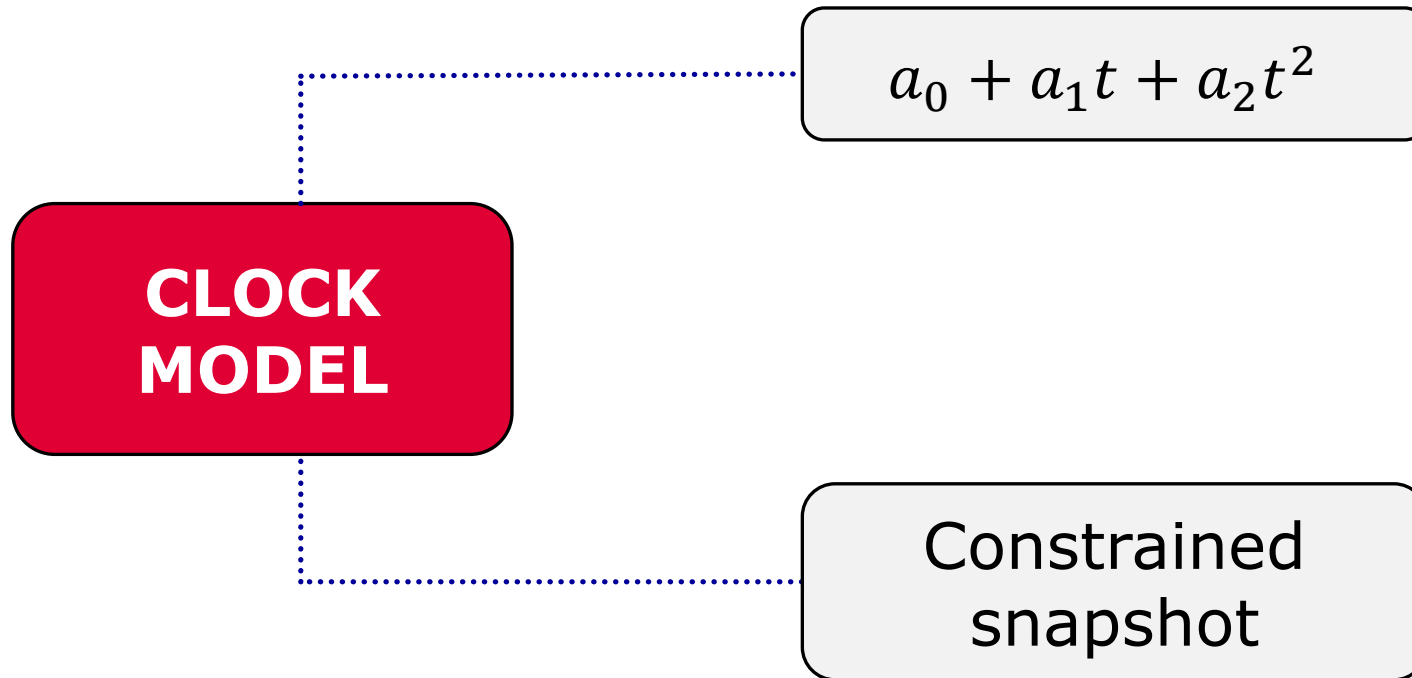
Stochastic

CLOCK MODELS IN ODTS



CLOCK MODELS IN magicODTS

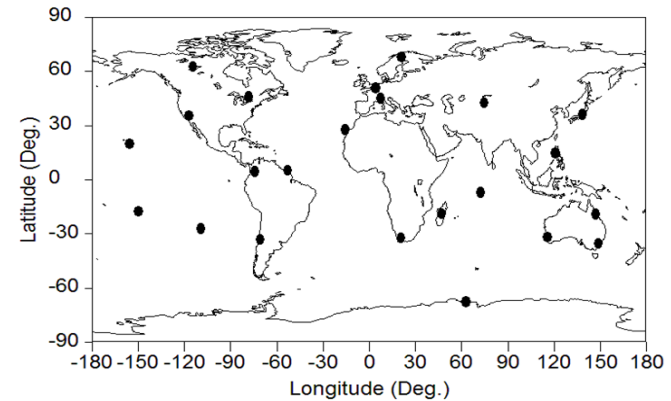
magicODTS enhanced with clock model est.



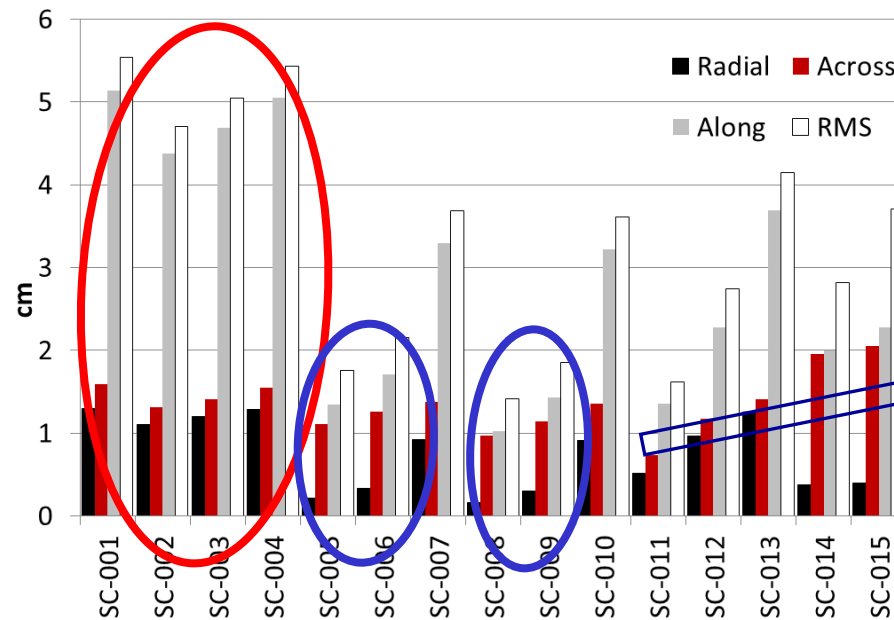
PRELIMINARY RESULTS

COVARIANCE ANALYSIS

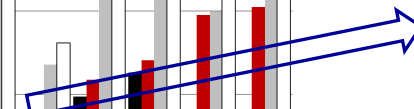
- Covariance analysis tool
- 23 stations network
- Different scenarios tried



Fix GSS
clocks



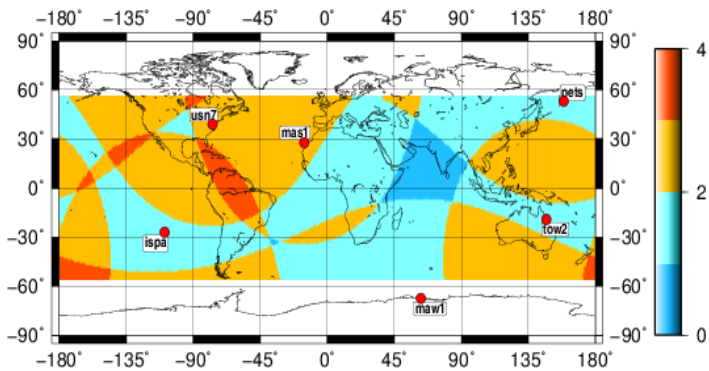
Fix SAT
clocks



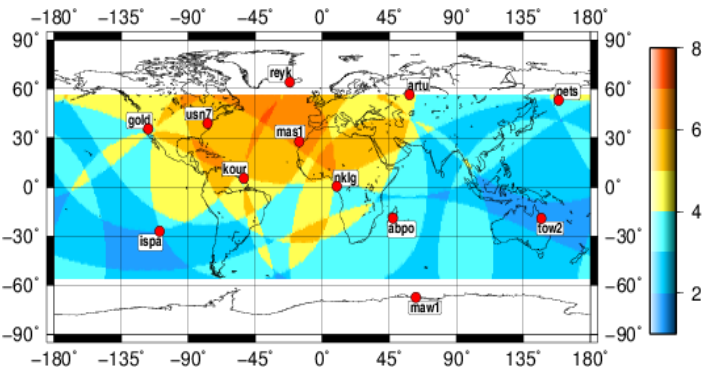
CLOCK MODELLING RESULTS

- magicODTS enhancement: each clock can be estimated as snapshot or clock model
- Clock model made of two parts $b(t) = b_G(t) + b_S(t)$
 - A quadratic function, $b_G(t) = a_0 + a_1t + a_2t^2$
 - A constrained snapshot correction, $b_S(t)$
- ODTs with clock model proved feasible, performance improvements for small networks

CLOCK MODELLING RESULTS



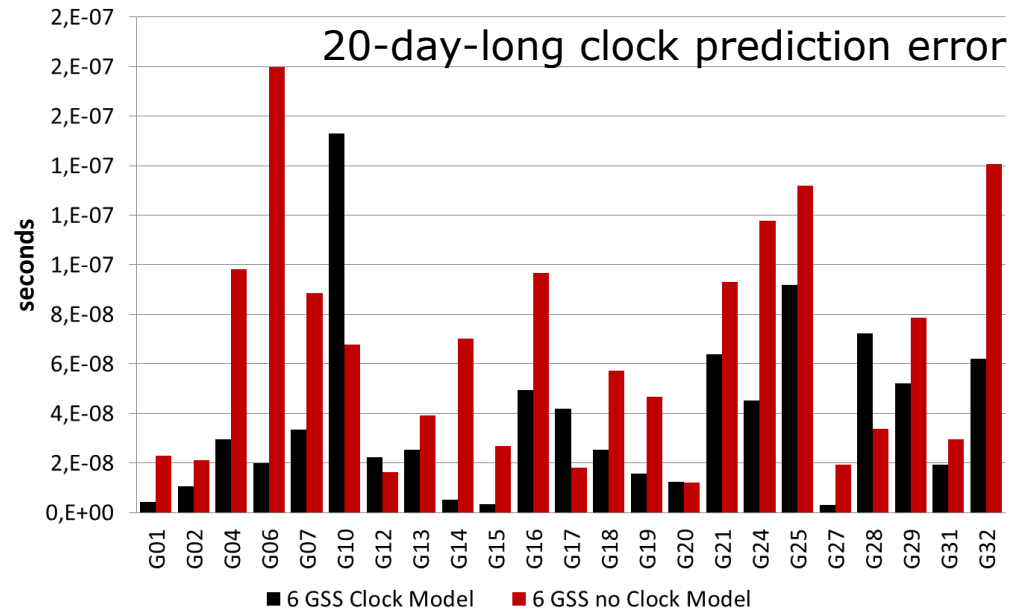
6 stations tracking network



12 stations tracking network

Orbit and Clock determination error wrt IGS

Processing type	CLK (ns)		ORB (cm)	
	6	12	6	12
Snapshot	0.51	0.26	21.3	6.6
Model	0.43	0.26	16.5	5.6



CONCLUSIONS

CONCLUSIONS

- Current GNSS clocks stability clears the path for potential performance improvements based on a tight modelling
- This would make possible to reduce tracking networks size
- Physical clock modelling in ODTs processing have shown positive results in reduced networks
- Systematic effects (e.g. thermal environment) need to be properly understood and modelled



Thank you

Pedro Francisco Navarro
GMV - GNSS BU
pfnavarro@gmv.com

Visit us at booths
118/120

gmV[®]
INNOVATING SOLUTIONS