

GNSS PPP WORKSHOP

# AN INDUSTRY APPROACH TO PRECISE POINT POSITIONING

JUNE 13<sup>TH</sup> , 2013 - GNSS PPP WORKSHOP, OTTAWA, CANADA

SESSION 4: USER SOLUTIONS

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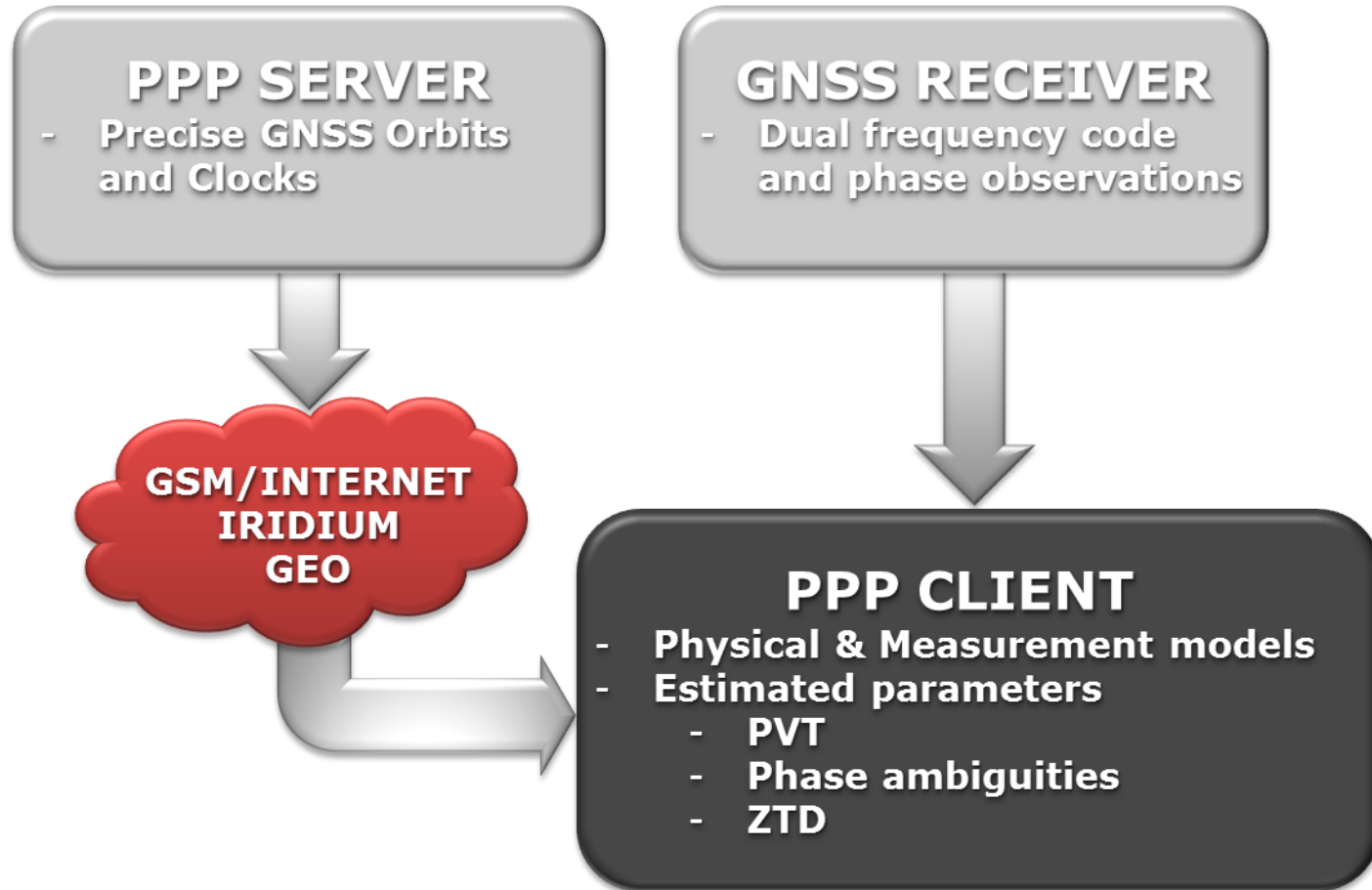
# OUTLINE

- Introduction
- PPP Infrastructure
  - Server
  - Client
- Testing on the field – highlights and lessons learned
- Regional PPP
- Galileo PPP
- PPP protection levels
- Conclusions

# INTRODUCTION



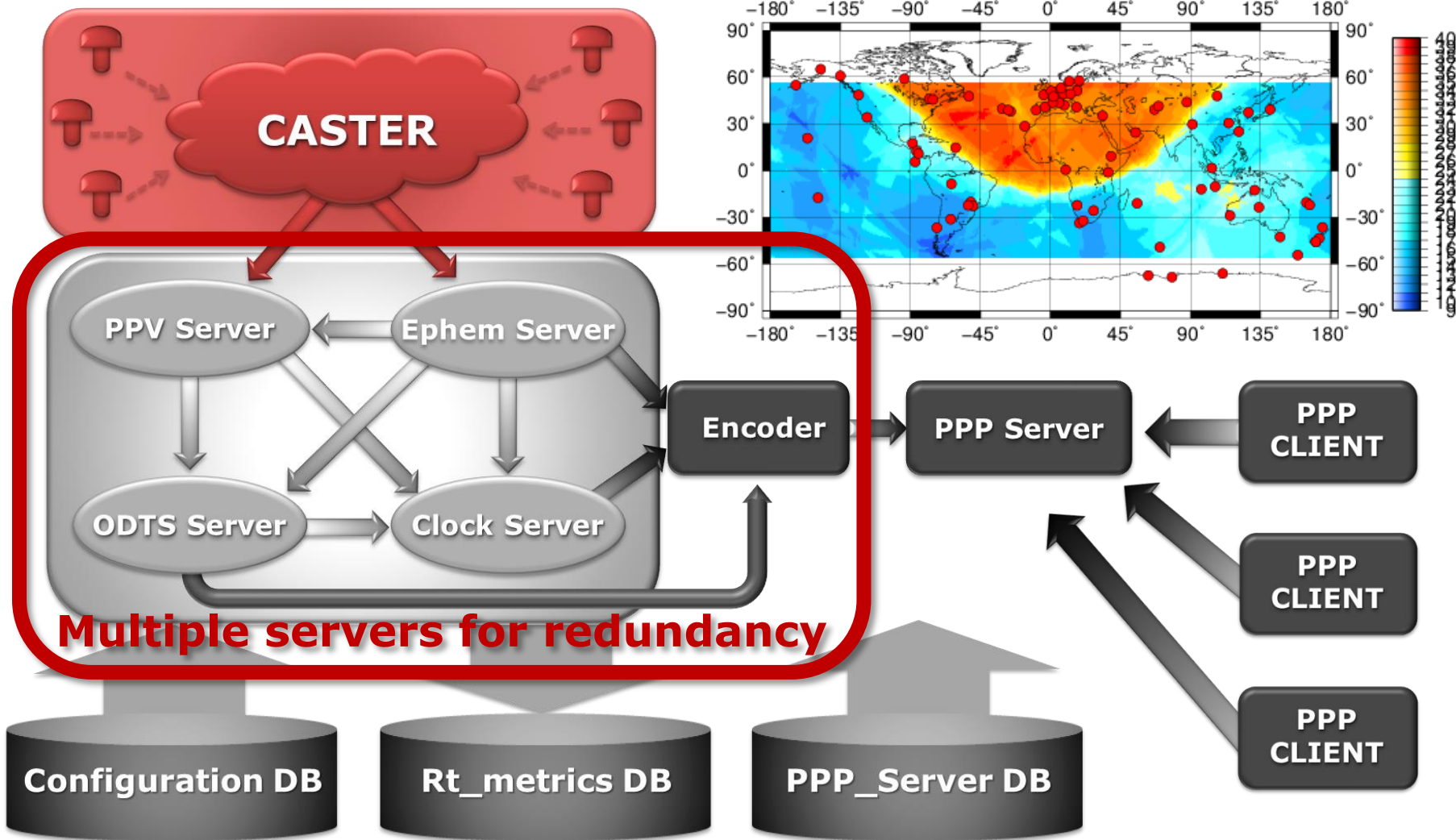
# PPP: PRECISE POINT POSITIONING



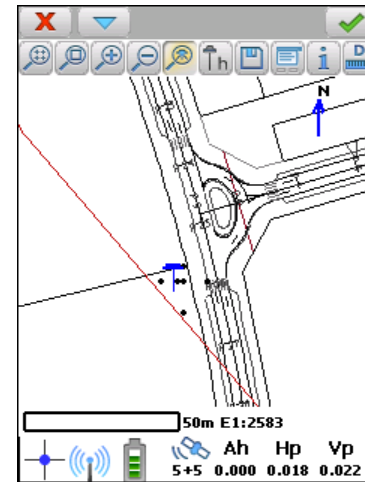
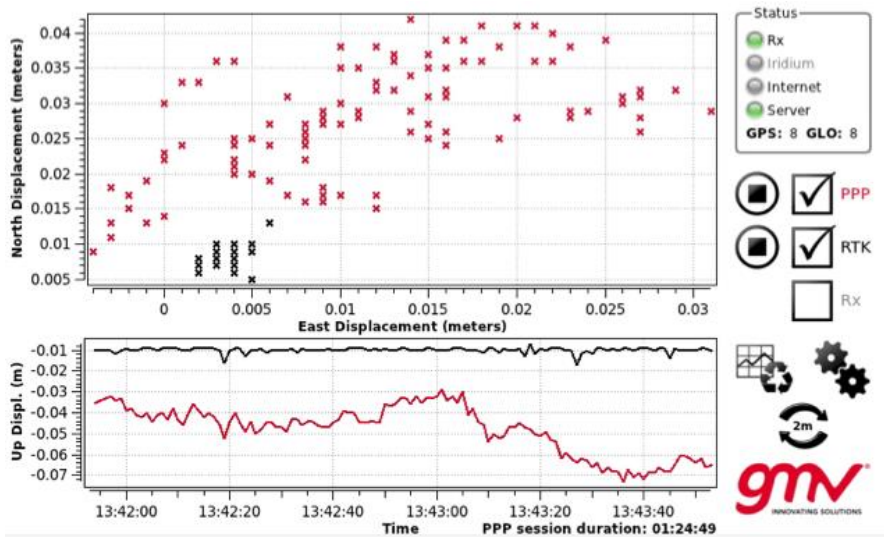
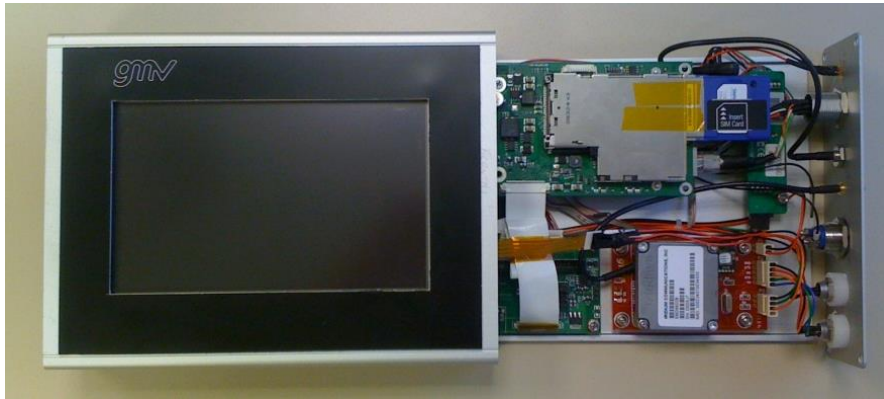
- Absolute positioning technique
- Precise orbits & clocks + observations + detailed models
- Sparse network of reference stations

# PPP INFRASTRUCTURE

# PPP DEMONSTRATOR SERVER



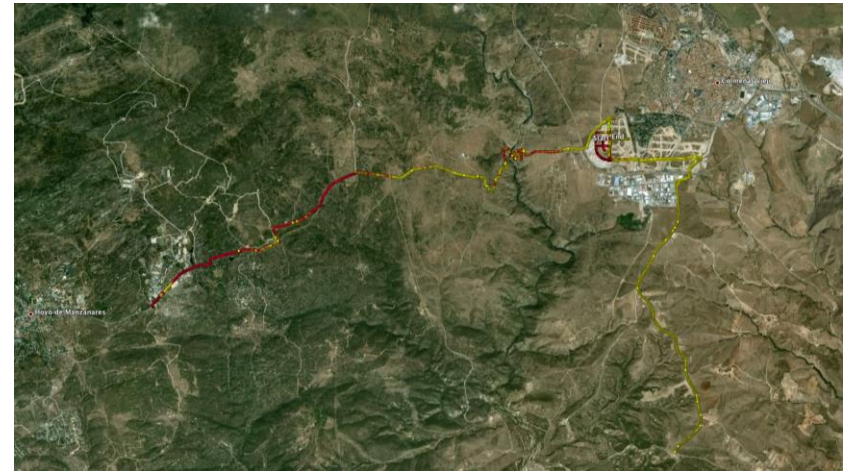
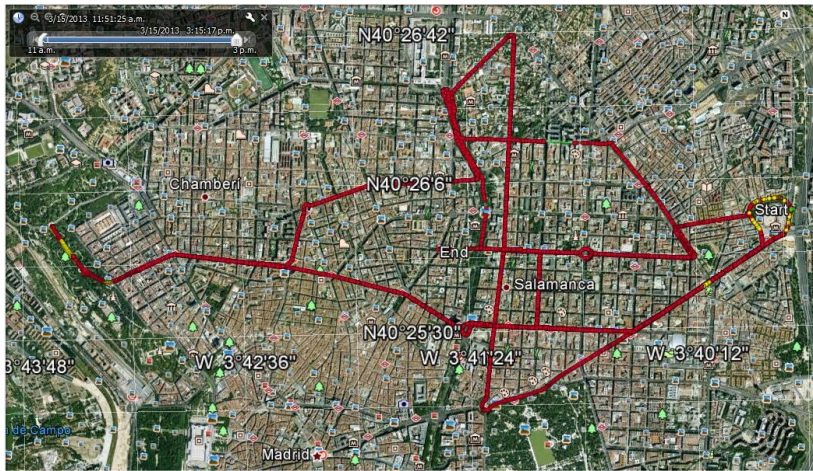
# RT PPP DEMONSTRATOR CLIENT



# PPP TESTING IN THE FIELD

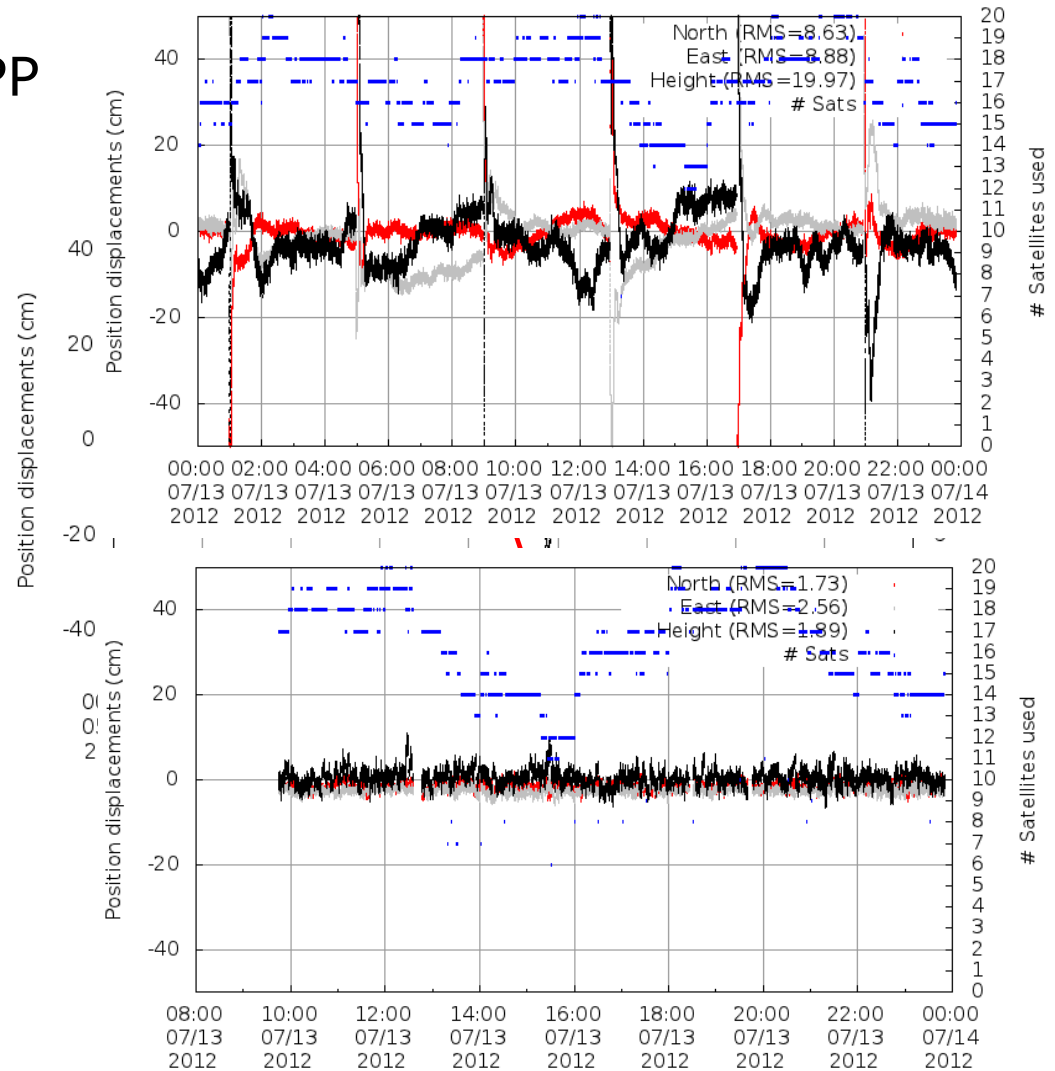


# KINEMATIC FIELD TESTS



# LEARNED EXPERIENCE

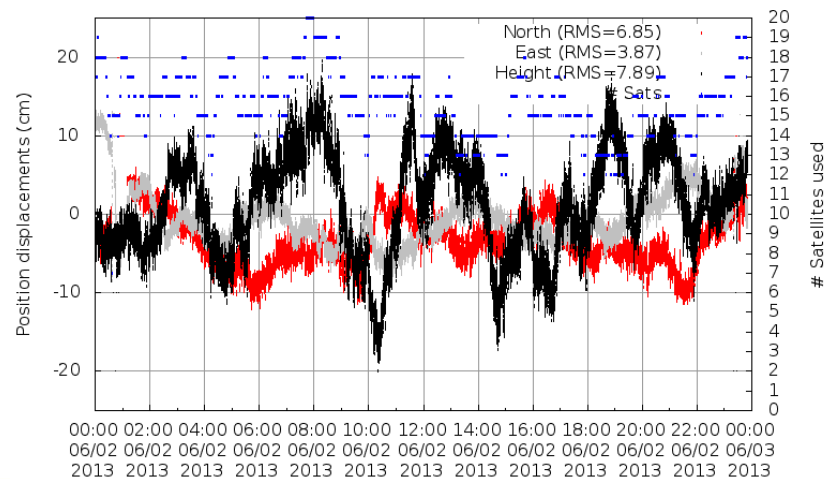
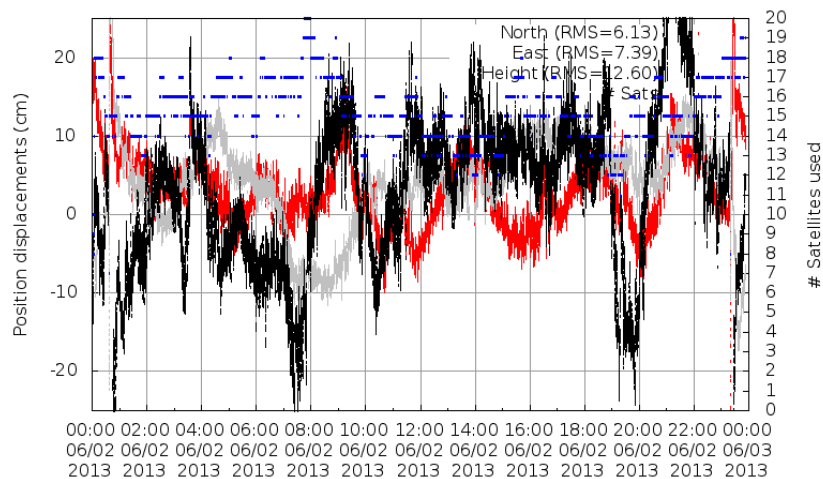
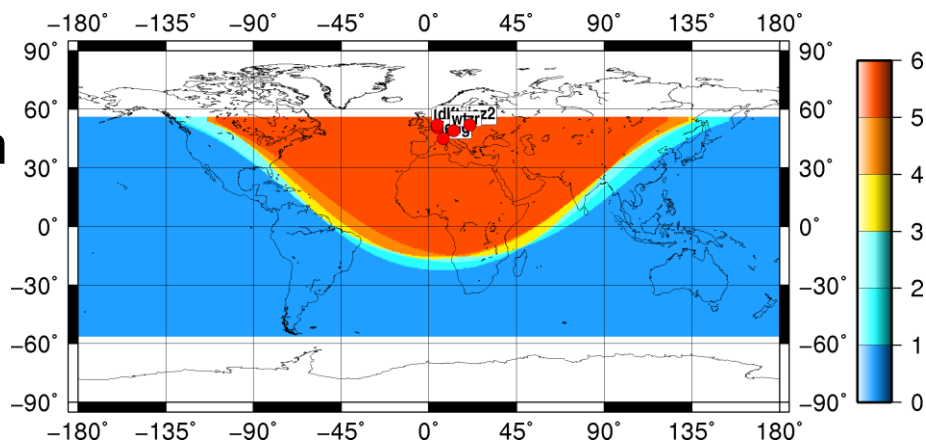
- Correction outages -> PPP products extrapolation.
- Loss of lines of sights
- Latency and Data rate performance impact
- Quickstart for certain applications



# REGIONAL PPP

# RREGIONAL PPP

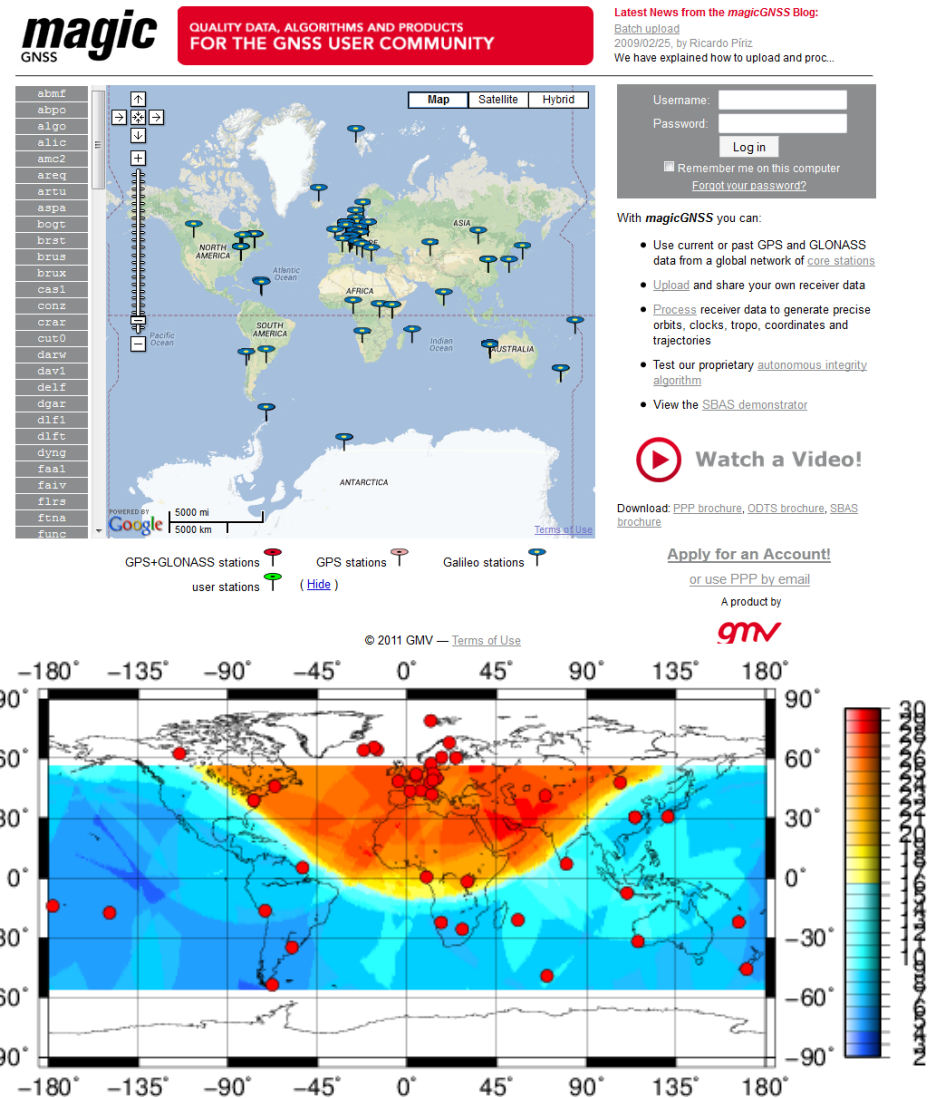
- Global network not always affordable -> Demonstrator server allows to easily set up a **regional network**.
- Real time PPP comparison
  - Global products
  - Regional products
- Slight degradation performances



# GALILEO PPP

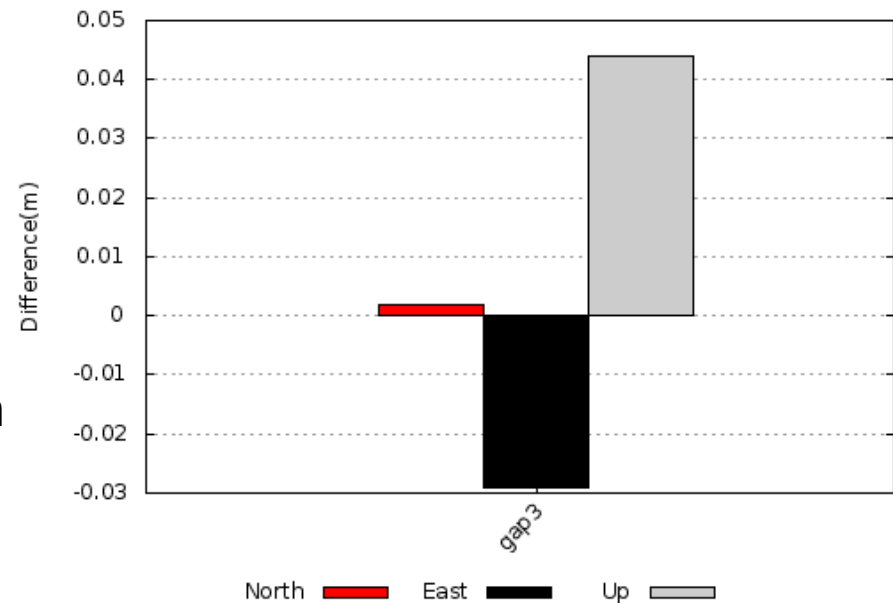
# GALILEO PPP (1)

- 4 operational Galileo satellites (E11, E12, E19 and E20) since late 2012.
- Large number of contributors to **MGEX** project (<http://igs.org/mgex/>) providing RINEX 3.0X and RTCM observations.
- IOVs disposition provides up to 3 hours of common view over Europe -> feasibility for PPP solutions.



# GALILEO PPP (2)

- TRIMBLE R10 receiver at GMVs premises.
- May 31<sup>st</sup>. 150 minute window with 4 IOV satellites over Tres Cantos.
- Postprocessing of the recorded RINEX data.
  - Static PPP based on IGS products for precise coordinate determination.
  - Galileo only static PPP based on GPS+Galileo products.
- Position error below 5 cm.

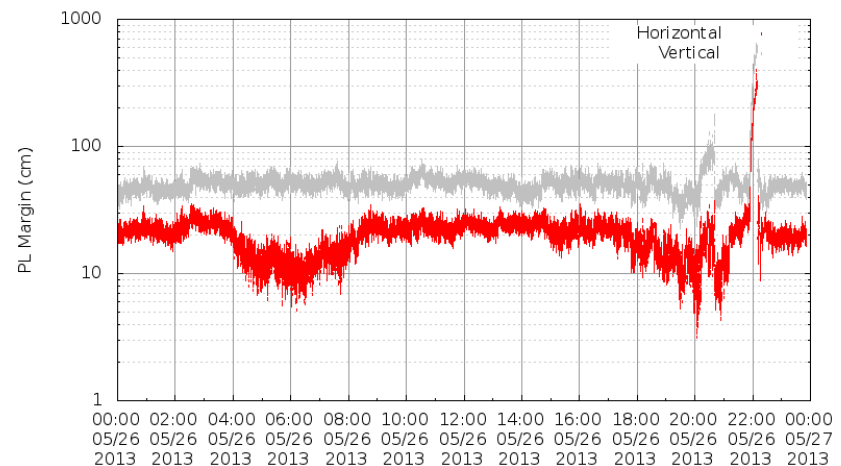
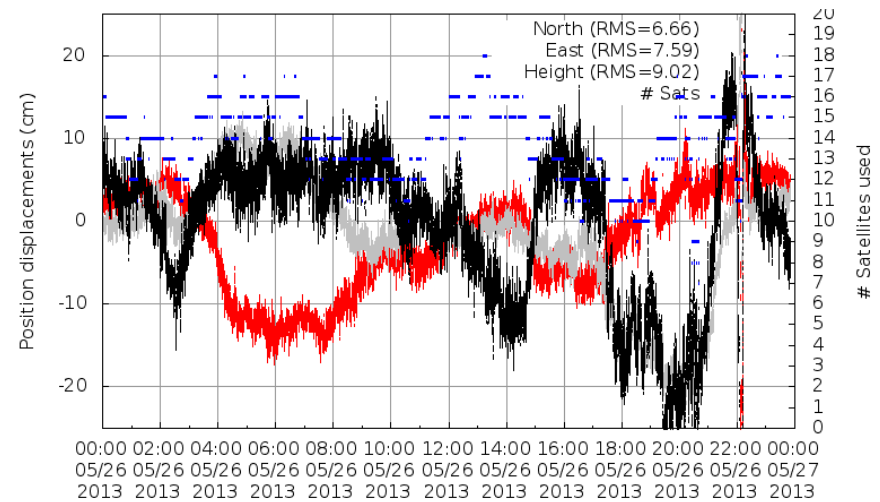


# PPP PROTECTION LEVELS



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- Based on process indicators and experimentation we generate a PL.
- Conservative approach for the definition of the PLs.
- Computed PLs bound the position error in nominal condition and under challenging environments.
- Intensive experimentation is foreseen.



# CONCLUSIONS

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- Full end user demonstration capability
  - Focused on robustness and operability
  - Enables to analyse different performance drivers
  - Extensive real-time field tests
  - Promising solutions for some of the main challenges
- Regional PPP: Feasible, promising results in real-time
- Galileo: Still proof of concept, but upcoming reality
- PL: Potential enabler for PPP applications



Thank you

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